## 6. Mechanism: Limited Direct Execution

**Operating System: Three Easy Pieces** 

## How to efficiently virtualize the CPU with control?

**D** The OS needs to share the physical CPU by time sharing.

Issue

- **Performance**: How can we implement virtualization without adding excessive overhead to the system?
- **Control**: How can we run processes efficiently while retaining control over the CPU?

**D** Just run the program directly on the CPU.

OS	Program
<ol> <li>Create entry for process list</li> <li>Allocate memory for program</li> <li>Load program into memory</li> <li>Set up stack with argc / argv</li> </ol>	
<ol> <li>Clear registers</li> <li>Execute call main()</li> </ol>	
	<pre>7. Run main() 8. Execute return from main()</pre>
<ol> <li>Free memory of process</li> <li>Remove from process list</li> </ol>	

Without *limits* on running programs, the OS wouldn't be in control of anything and thus would be "just a library"

- What if a process wishes to perform some kind of restricted operation such as ...
  - Issuing an I/O request to a disk
  - Gaining access to more system resources such as CPU or memory

- **Solution**: Using protected control transfer (processor has to support it)
  - User mode: Applications do not have full access to hardware resources.
  - Kernel mode: The OS has access to the full resources of the machine

- Allow the kernel to carefully expose certain key pieces of functionality to user program, such as ...
  - Accessing the file system
  - Creating and destroying processes
  - Communicating with other processes
  - Allocating more memory

But, why they look like a regular procedure call "sometimes" (e.g. libc calls)?

#### **Trap** instruction

- Jump into the kernel (how to tell where?)
- Raise (the processor) privilege level to kernel mode
- **Return-from-trap** instruction
  - Return into the calling user program
  - Reduce (the processor) privilege level back to user mode

## Limited Direction Execution Protocol

OS @ boot (kernel mode)	Hardware	
initialize trap table	remember address of syscall handler	
OS @ run (kernel mode)	Hardware	Program (user mode)
Create entry for process list Allocate memory for program Load program into memory Setup user stack with argv Fill kernel stack with reg/PC <b>return-from -trap</b>	restore regs from kernel stack move to user mode jump to main	Run main()  Call system <b>trap</b> into OS

## Limited Direction Execution Protocol (Cont.)

OS @ run (kernel mode)	Hardware	Program (user mode)
	(Cont.)	
Handle trap	save regs to kernel stack move to kernel mode jump to trap handler	
Do work of syscall return-from-trap	restore regs from kernel stack move to user mode jump to PC after trap	
		 return from main trap (via exit())
Free memory of process Remove from process list		• • • • • •

## **Problem 2: Switching Between Processes**

- How can the OS regain control of the CPU so that it can switch between *processes*?
  - A cooperative Approach: Wait for system calls
  - A Non-Cooperative Approach: **The OS takes control**

## A cooperative Approach: Wait for system calls

- Processes periodically give up the CPU by making system calls such as yield.
  - The OS decides to run some other task.
  - Application also transfer control to the OS when they do something illegal.
    - Divide by zero
    - Try to access memory that it shouldn't be able to access
  - Ex) Early versions of the Macintosh OS, The old Xerox Alto system

#### A process gets stuck in an infinite loop. → Reboot the machine

#### A timer interrupt

- During the boot sequence, the OS start the <u>timer</u> (hardware).
- The timer <u>raise an interrupt</u> every so many milliseconds. (hardware)
- When the interrupt is raised :
  - The currently running process is halted.
  - Save enough of the state of the program
  - A pre-configured interrupt handler in the OS runs.

# A timer interrupt gives OS the ability to run again on a CPU.

## Saving and Restoring Context

- **Scheduler** makes a decision:
  - Whether to continue running the current process, or switch to a different one.
  - If the decision is made to switch, the OS executes context switch.

- A low-level piece of assembly code
  - Save a few register values for the current process onto its kernel stack
    - General purpose registers
    - o PC
    - kernel stack pointer
  - **Restore a few** for the soon-to-be-executing process from its kernel stack
  - Switch to the kernel stack for the soon-to-be-executing process

#### Limited Direction Execution Protocol (Timer interrupt)

OS @ boot (kernel mode)	Hardware	
initialize trap table	remember address of syscall handler	
start interrupt timer	timer handler	
	start timer interrupt CPU in X ms	
OS @ run (kernel mode)	Hardware	Program (user mode)
		Process A
	<b>timer interrupt</b> save regs(A) to k-stack(A) move to kernel mode	

#### Limited Direction Execution Protocol (Timer interrupt)

OS @ run (kernel mode)	Hardware	Program (user mode)
	(Cont.)	
Handle the trap Call switch() routine save regs(A) to proc-struct(A) restore regs(B) from proc-struct(B) switch to k-stack(B) <b>return-from-trap (into B)</b>		
	restore regs(B) from k-stack(B) move to user mode jump to B's PC	
		Process B

## The xv6 Context Switch Code

```
1 # void swtch(struct context **old, struct context *new);
2. #
3 # Save current register context in old
4 # and then load register context from new.
5 .qlobl swtch
6 swtch:
         # Save old registers
7
8
         movl 4(%esp), %eax
                              # put old ptr into eax
9
         popl 0(%eax)
                                 # save the old IP (pop from stack to mem)
                                 # and stack
10
         movl %esp, 4(%eax)
                                # and other registers
         movl %ebx, 8(%eax)
11
12
         movl %ecx, 12(%eax)
13
         movl %edx, 16(%eax)
         movl %esi, 20(%eax)
14
15
         movl %edi, 24(%eax)
16
         movl %ebp, 28(%eax)
17
18
         # Load new registers
19
         movl 8(%esp), %eax  # put new ptr into eax
20
         movl 28(%eax), %ebp
                                   # restore other registers
21
         movl 24(%eax), %edi
2.2
         movl 20(%eax), %esi
23
         movl 16(%eax), %edx
24
         movl 12(%eax), %ecx
25
         movl 8(%eax), %ebx
2.6
                                # stack is switched here
         movl 4(%eax), %esp
27
         pushl 0(%eax)
                                      # return addr put in place
28
                                      # finally return into new ctxt
         ret
```

### Current xv6 Code

```
Context switch
   void swtch(struct context **old, struct context *new);
 Save current register context in old
 and then load register context from new.
globl swtch
swtch:
 movl 4(%esp), %eax
 movl 8(%esp), %edx
 # Save old callee-save registers
 pushl %ebp
 pushl %ebx
 pushl %esi
 pushl %edi
 # Switch stacks
 movl %esp, (%eax)
 movl %edx, %esp
 # Load new callee-save registers
 popl %edi
 popl %esi
 popl %ebx
 popl %ebp
```

No actual change

to new %eip, because
we need to "switch"
memory addressing
space before
(done in the scheduler
switchkvm();)

In proc.h

// Don't need to save %eax, %ecx, %edx, because the 46

// x86 convention is that the caller has saved them.

- What happens if, during interrupt or trap handling, another interrupt occurs?
- **o** OS handles these situations:
  - **Disable interrupts** during interrupt processing
  - Use a number of sophisticate **locking** schemes to protect concurrent access to internal data structures.

 Disclaimer: This lecture slide set is used in AOS course in University of Cantabria. Was initially developed for Operating System course in Computer Science Dept. at Hanyang University. This lecture slide set is for OSTEP book written by Remzi and Andrea Arpaci-Dusseau (at University of Wisconsin)